

Module 1: Matrices & Eigenvalues

Week 3 Tutorial

Matrix diagonalization

Key goals for the class

1. How do we **diagonalize** a matrix and why is this useful?
2. How can we **reconstruct a matrix** knowing its eigenvalues and eigenvectors?
3. What are the special properties of **symmetric matrices**?
4. How do we represent a **quadratic curve** using a matrix equation, and determine what sort of curve it represents?

Diagonal matrices

A **diagonal matrix** only contains non-zero entries in the diagonal elements:

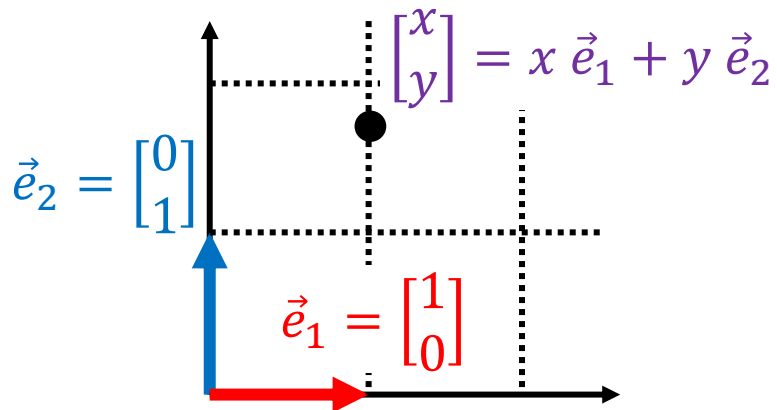
Diagonal matrix

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 8 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

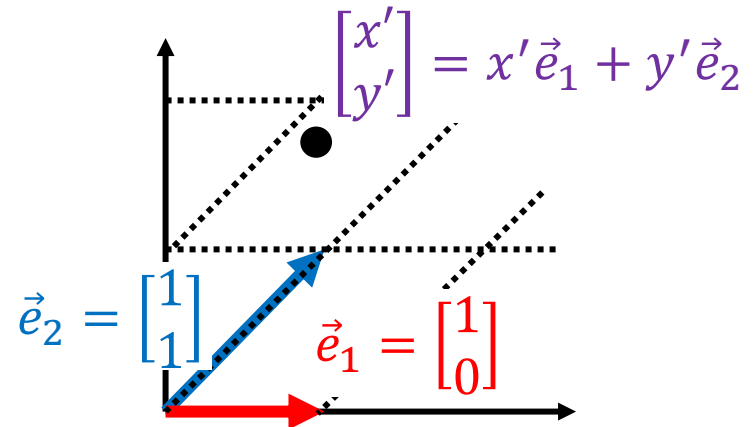
Diagonal matrices are very nice to use for matrix operations like multiplications or inverses!

Basis vectors

Basis vectors are linearly independent vectors that span our co-ordinate space, for example:



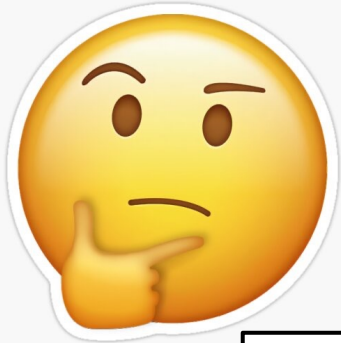
We may choose **another set** of basis vectors, for example:



The **change of basis matrix** $\mathbf{B} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ transforms the co-ordinates of a point between the different bases: $\vec{x} = \mathbf{B} \vec{x}'$

A **linear transformation** \mathbf{A} in one basis can be expressed in the co-ordinate system of the new basis as $\mathbf{B}^{-1} \mathbf{A} \mathbf{B}$

What is matrix diagonalization?



A matrix represents a **linear transformation**

Diagonalizing a matrix means **finding the basis in which this transformation is a diagonal matrix**

This basis is given by the **eigenvectors**, and the transformation is a scaling by the **eigenvalues**

Key formula for diagonalization

If \mathbf{A} is an $n \times n$ matrix with an eigenvalue **spectrum** $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$ and eigenvectors $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, then

$$\mathbf{M}^{-1} \mathbf{A} \mathbf{M} = \mathbf{\Lambda}$$

Modal matrix $\mathbf{M} = \begin{bmatrix} | & | & | \\ \vec{v}_1 & \vec{v}_2 & \vec{v}_n \\ \downarrow & \downarrow & \downarrow \end{bmatrix}$ **Spectral matrix** $\mathbf{\Lambda} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_n \end{bmatrix}$

- To **reconstruct a matrix** from its eigen-things: $\mathbf{A} = \mathbf{M} \mathbf{\Lambda} \mathbf{M}^{-1}$
- If \mathbf{A} is a **symmetric matrix** (see below), then $\mathbf{M}^{-1} = \mathbf{M}^T$
- \mathbf{A} is diagonalizable if its eigenvectors are **linearly independent**

Tutorial question

Try Q1 on the tutorial sheet (**practising the matrix diagonalization formula**).

- 1. In Tutorial 2 we have shown that the eigenvalues of the matrix

$$A = \begin{bmatrix} 4 & -1 \\ 2 & 1 \end{bmatrix}$$

are given by $\lambda = 2, 3$. The corresponding eigenvectors are

$$\mathbf{v}_{(\lambda=2)} = t \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad t \in (-\infty, \infty) \quad \mathbf{v}_{(\lambda=3)} = s \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad s \in (-\infty, \infty).$$

- (a) Write down the modal matrix M .
- (b) Find the inverse M^{-1} .
- (c) Show that

$$M^{-1}AM = \Lambda,$$

where Λ is the spectral matrix.

Symmetric matrices

What is a **symmetric matrix**?

What is special about the eigenvalues and eigenvectors of a symmetric matrix?

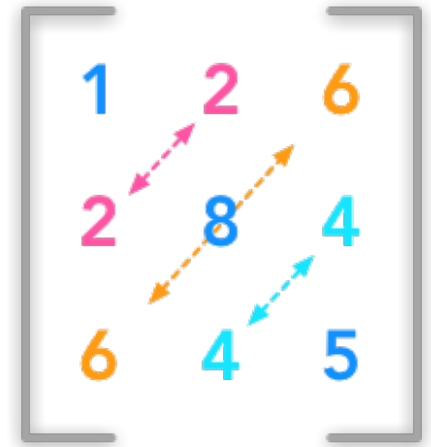
Symmetric matrices

What is a **symmetric matrix**?

Transpose is equal to the original matrix!

$$\mathbf{A}^T = \mathbf{A}$$

Symmetric matrix



Special properties of symmetric matrices:

1. Eigenvalues are **real numbers** (not complex)
2. Eigenvectors are **orthogonal** (means that $\mathbf{M}^{-1} = \mathbf{M}^T$)
3. An $n \times n$ symmetric matrix always has **n eigenvectors**

Tutorial question

Try Q2 on the tutorial sheet (**symmetric matrix example**).

- 2. The eigenvectors of the symmetric matrix

$$A = \begin{bmatrix} 3 & 0 & -2 \\ 0 & 2 & 0 \\ -2 & 0 & 0 \end{bmatrix}$$

are given by

$$\mathbf{v}_1 = t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = s \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \quad \mathbf{v}_3 = p \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \quad t, s, p \in (-\infty, \infty).$$

- (a) Normalize the eigenvectors and write down the modal matrix M .
- (b) Show that the eigenvectors that correspond to distinct eigenvalues are orthogonal.
- (c) Calculate

$$M^T A M$$

and thus, determine all eigenvalues of A .

Quadratic curves

A **quadratic curve** (in 2D) has an equation of the form

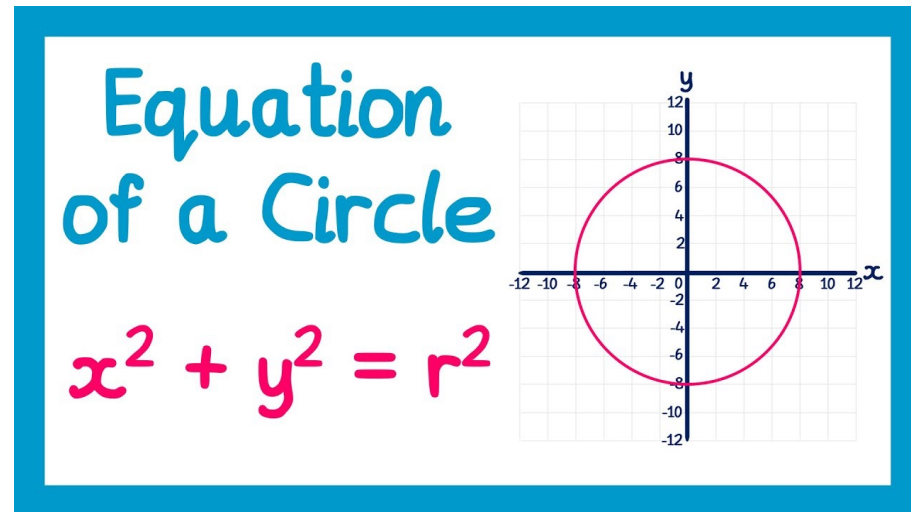
$$ax^2 + by^2 + 2cxy = 1$$

It can be expressed in **matrix form** by writing

$$\vec{x}^T \mathbf{A} \vec{x} = 1$$

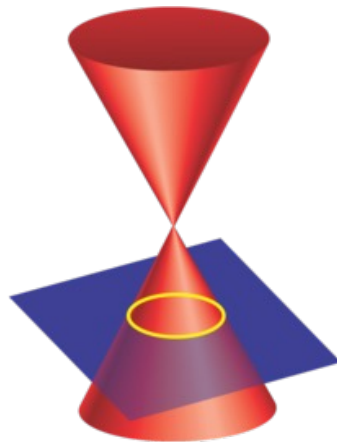
where $\vec{x} = \begin{bmatrix} x \\ y \end{bmatrix}$ and $\mathbf{A} = \begin{bmatrix} a & c \\ c & b \end{bmatrix}$

The type of surface can be found from the matrix \mathbf{A}

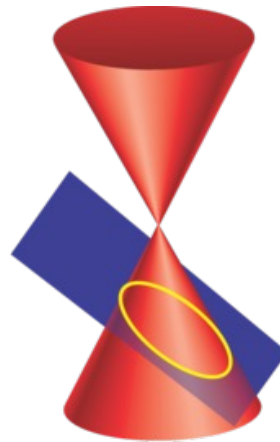


Quadratic curves

What other types of curve can
 $ax^2 + by^2 + 2cxy = 1$ represent?



circle



ellipse



hyperbola

Tutorial question

Try Q3 on the tutorial sheet (**quadratic curve**).

3. Identify the type of the quadratic curve given by

$$5x^2 - 2\sqrt{3}xy + 7y^2 = c$$

where c is a constant.

Does the type of the curve depend on $c > 0$?

What happens if $c < 0$?

Tutorial question

Try Q4 on the tutorial sheet (if time).

- 4. (a) Draw the curve from Q3 and determine the directions of the axes of symmetry.

- (b) There exists an orthogonal linear transformation of coordinates (x, y)

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix},$$

that transforms the quadratic curve in Q3 into its canonical form. Determine the matrix $\begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$ and write down the quadratic curve in the new coordinates (x', y') . Give geometric interpretation for the transformation used.

- (c) Discuss the difference between two similarity transformations that we use to diagonalize a matrix A : $M^{-1}AM = \Lambda$ and $M^TAM = \Lambda$.

That's all for today!