#### **Class 4: Accelerated Motion**

In this class we will investigate how accelerated motion can be studied within Special Relativity; in the next class we'll discuss how this is equivalent to motion in a gravitational field

#### **Class 4: Accelerated Motion**

At the end of this session you should be able to ...

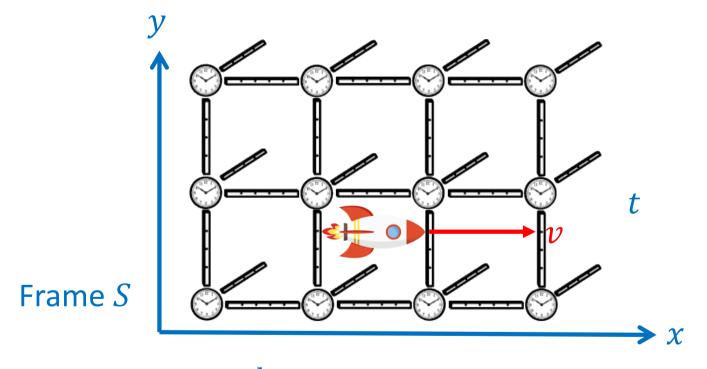
- ... determine the world line of an accelerated object in special relativity
- ... represent this motion on a space-time diagram
- ... describe how the **clock rate varies** within a long rocket ship undergoing accelerated motion

• One of the centre-pieces of classical physics is Newton's 2<sup>nd</sup> Law:  $\vec{F} = m\vec{a}$ 



• What does acceleration look like in Special Relativity?

• What does uniform acceleration look like in frame S?



- Initial guess :  $\frac{dv}{dt} = \text{constant} \rightarrow v = v_0 + at$
- Does this make sense??

- No velocity will eventually exceed *c*!
- No "dv" involves subtracting velocities at nearby points, but we know velocities add in strange ways in relativity!
- No "dt" involves time intervals, but these vary between frames
- $\frac{dv}{dt}$  = constant is unphysical and can't hold in all frames

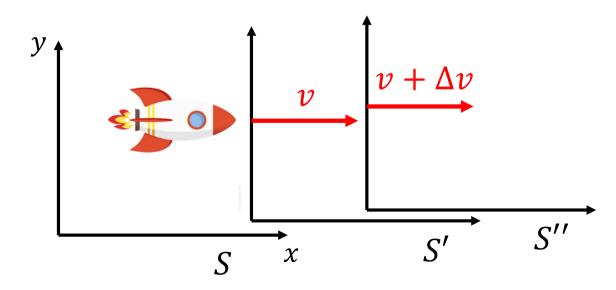
 Let's define uniform acceleration in a different way – as "feeling constant to the object being accelerated"



https://www.decodedscience.org/jet-airplanes-take-off-speeds-and-aircraft-performance/5453

• (The accelerated observer can always measure this rate by gently dropping a rock out of the window)

- How can we analyze this in terms of inertial frames?
- Set up a large number of inertial frames with a range of relative velocities, such that the accelerating object is temporarily at rest in each – analyze the motion by patching all the frames together



• We define constant proper acceleration by

$$\alpha = \frac{dv'}{d\tau} = \text{constant}$$

 $d\tau =$  proper time elapsed on the rocket-ship clock in a small interval (= dt' in S')

dv' = momentary increase in speed from rest in S' (non-relativistic, since initially v' = 0)

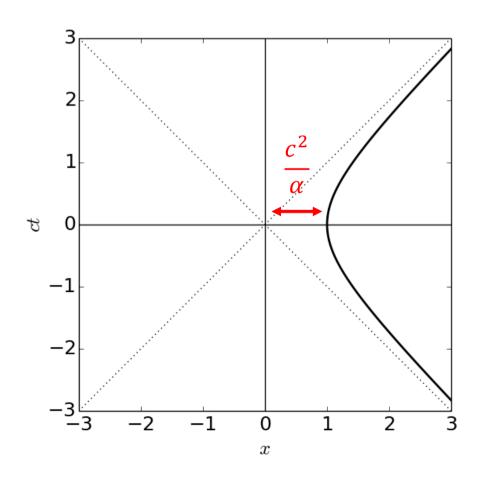
# World line of accelerating object

- We can determine the space-time co-ordinates x(t) of the rocket-ship in the original frame S, in terms of the proper time co-ordinate  $\tau$  in the ship's rest frame
- The velocity in S is  $v = c \tanh\left(\frac{\alpha \tau}{c}\right)$  at large times  $v \to c$ , but the ship's speed never exceeds c
- The *t* co-ordinate in *S* is  $t = \frac{c}{\alpha} \sinh\left(\frac{\alpha \tau}{c}\right)$

• The x co-ordinate in S is 
$$x = \frac{c^2}{\alpha} \cosh\left(\frac{\alpha \tau}{c}\right)$$

#### Accelerating space-time diagram

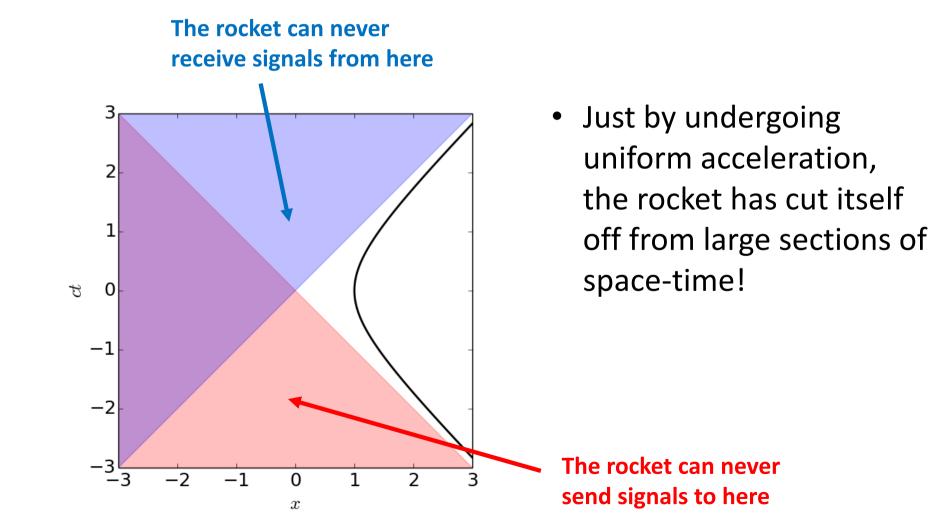
• Uniformly-accelerated objects are moving along a hyperbola in a space-time diagram,  $x^2 - (ct)^2 = (c^2/\alpha)^2$ 



- The object remains a constant proper distance from the origin (sounds confusing, but this is a distance in space-time, not space!)
- The object's space-time diagram is the same in every frame (whenever it enters my frame at v = 0, I find its acceleration to be α)

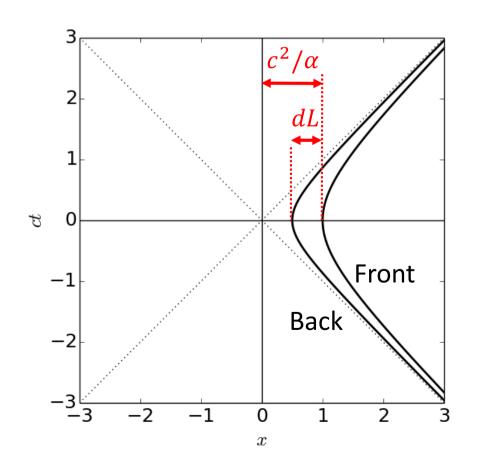
# Accelerating space-time diagram

• Consider this rocket sending and receiving light signals



#### Clock rates in a rocket ship

• Now consider a "long rocket", such that its front and back have different world lines, but are separated by a fixed proper length dL at any instant (i.e., dx = dL when dt = 0)



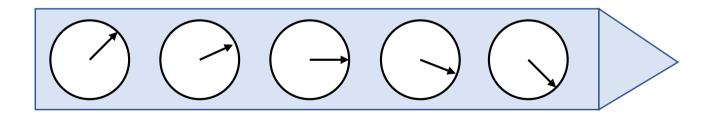
• The proper accelerations of the front and back must be different!

• 
$$\frac{c^2}{\alpha_F} - \frac{c^2}{\alpha_B} = dL$$

•  $\alpha_F < \alpha_B$ 

## Clock rates in a rocket ship

- Synchronize the front and back observer clocks at  $\tau = 0$ , when the rocket is instantaneously at rest in S
- At some later instant when the rocket is at rest in S',  $v = c \tanh(\alpha \tau/c)$  for both ends. But  $\alpha$ 's are different!  $\rightarrow \frac{\Delta \tau_F}{\Delta \tau_B} = \frac{\alpha_B}{\alpha_F}$
- More proper time has elapsed at the front of the rocket! The front clocks are running "faster"!



• This phenomenon occurs in *the accelerating frame of the long rocket* – it's **not an inertial frame**, so does not contradict SR