

# Class 1: Special Relativity

*In this class we will review some important concepts in Special Relativity, that will help us build up to the General theory*

# Class 1: Special Relativity

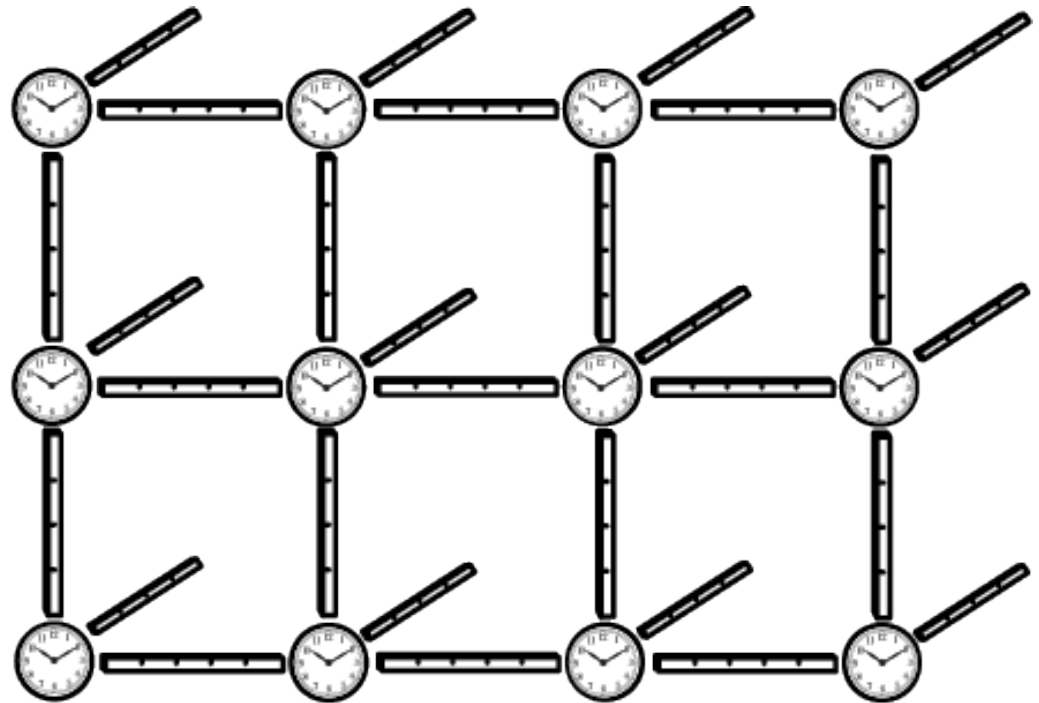
At the end of this session you should ...

- ... **be familiar with the basic ingredients of Special Relativity:** reference/inertial frames, the Lorentz transformations, Einstein's postulate and its consequences
- ... **understand the significance of the space-time interval  $ds^2$**  between two events
- ... **be able to use space-time diagrams** to describe some simple visualizations of events in space-time
- ... **understand how the definitions of classical momentum and energy** must be modified in Special Relativity

# Reference frames

- How do we describe occurrences in nature?

- A **reference frame** is an information-gathering system consisting of a field of synchronized clocks on a coordinate grid

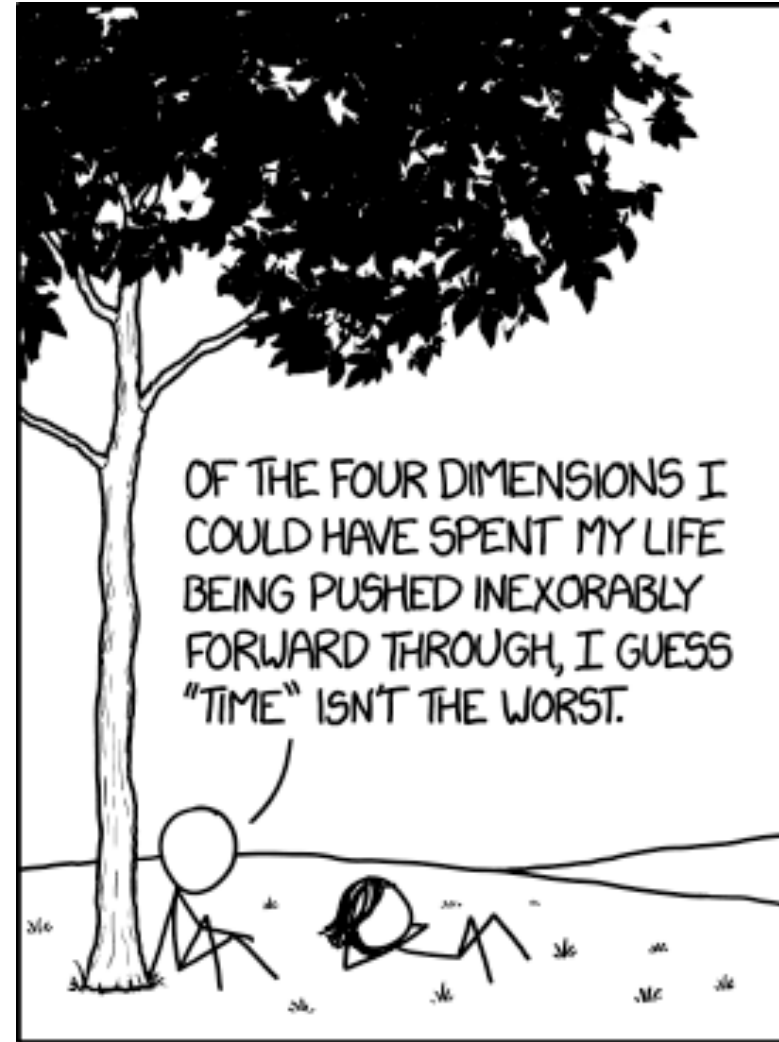


[http://www.pitt.edu/~jdnorton/teaching/HPS\\_0410/chapters/Special\\_relativity\\_principles](http://www.pitt.edu/~jdnorton/teaching/HPS_0410/chapters/Special_relativity_principles)

- An **event** is an occurrence with definite location/time

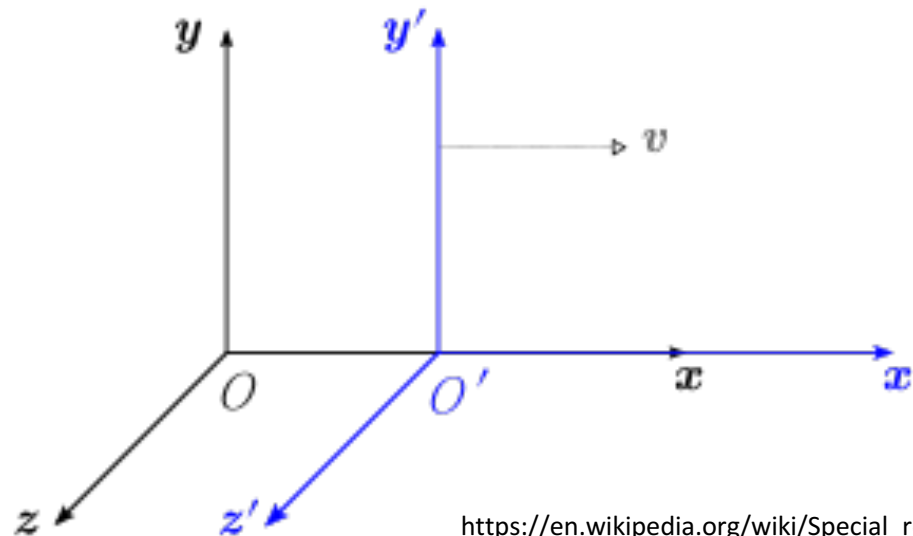
# Reference frames

- The locations and times of events together form a 4D co-ordinate system known as **space-time**.



# Inertial frames

- Some reference frames are special
- In an **inertial frame**, a freely-moving body (no external forces) moves with constant velocity
- Inertial frames **move uniformly** with respect to each other



# Inertial frames

- Some examples of non-inertial frames!



<https://www.thinglink.com/scene/877700809561735169>

<https://www.pinterest.com.au/bestonamusement/beston-frisbee-rides-for-sale-or-fairground-pendul/>

# Principle of relativity

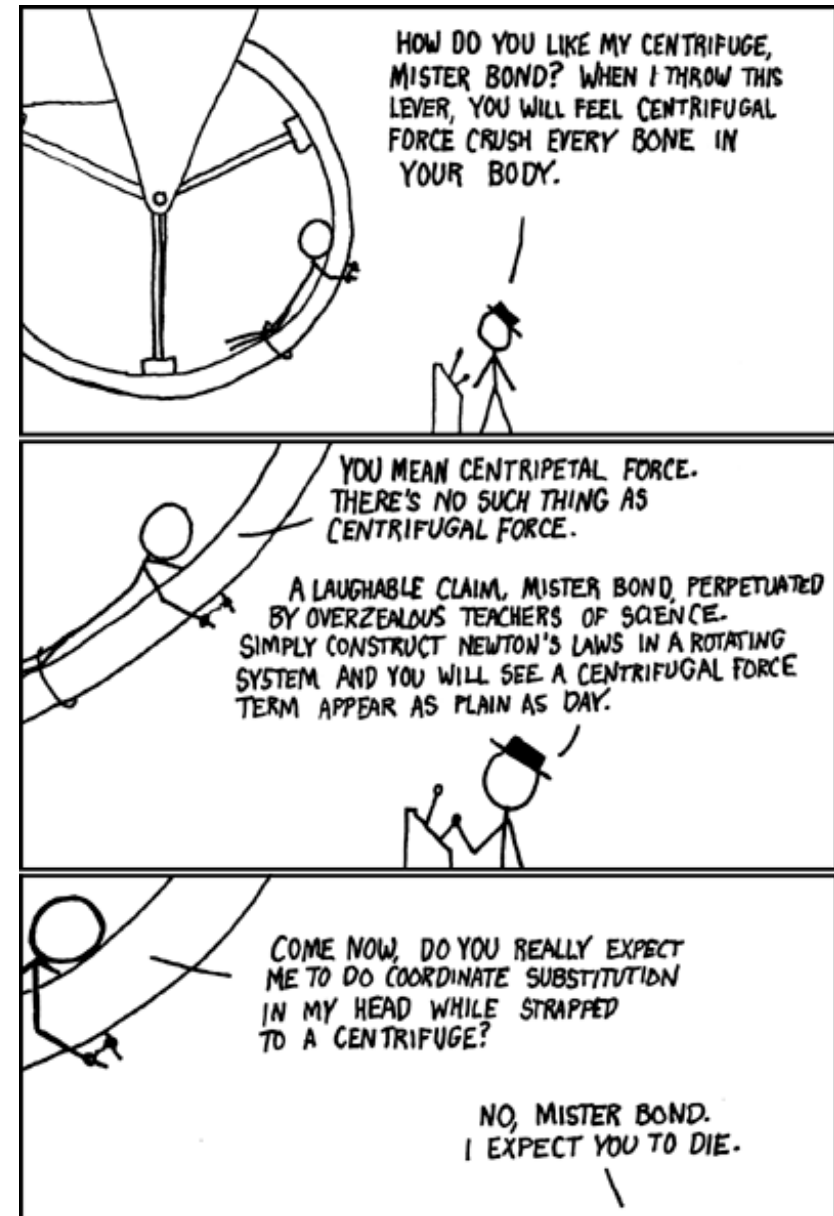
- **Laws of nature are identical in all inertial frames** (mathematically, they have the same form in each frame's co-ordinate system)
- There is no such thing as **absolute** rest/velocity

(Due to Galileo)



# Principle of relativity

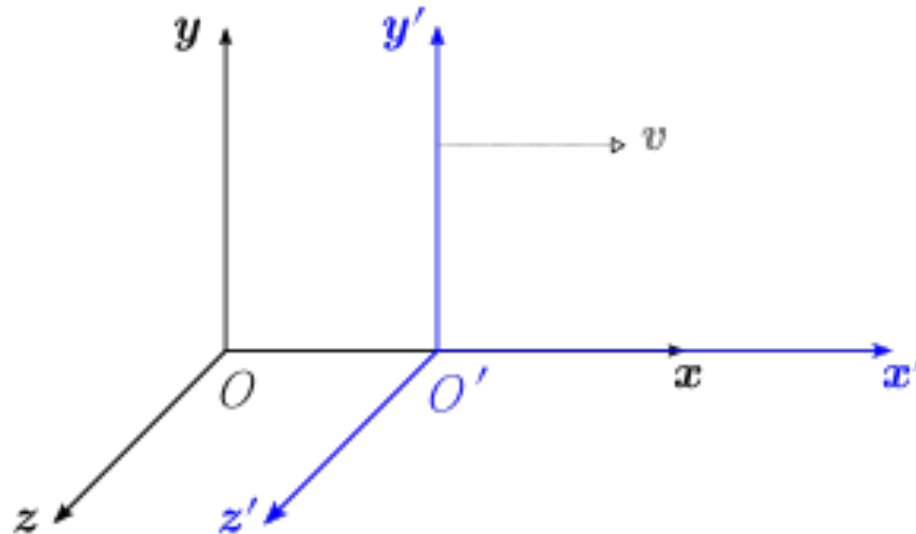
- **Example:** Newton's Laws  $\vec{F} = m\vec{a}$  are invariant under the transformation  $\vec{v}'(t) = \vec{v}(t) + V_{constant}$
- **Not true for non-inertial frames**, in which we experience forces we cannot account for





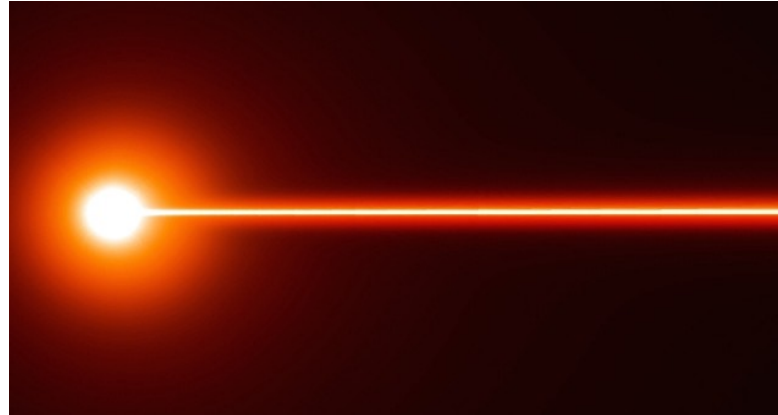
# Transformations between frames

- If  $(t, x, y, z)$  are the co-ordinates of an event in frame  $S$ , what are its co-ordinates  $(t', x', y', z')$  in frame  $S'$  moving with speed  $v$  with respect to  $S$ ?



- **Galilean transformation:** clocks in  $S$  and  $S'$  run at the same rate ( $t' = t$ ), and velocities add ( $u = u' + v$ )

# The role of light



<https://brooklyntomars.com/laser-beam-focus-352154e6acaf>

- According to the Galilean transformation, the speed of light  $c$  slows down to  $c - v$  in  $S'$
- **This can be tested experimentally and is false** (e.g. Michelson-Morley experiment)
- The Galilean transformation is **inconsistent with electromagnetism**

# The role of light

- In classical physics, **interactions are instantaneous** (change in one thing instantaneously affects another)
- **This is not true** – there is a finite maximum velocity at which interactions propagate, which turns out to be the speed of light  $c = 3 \times 10^8$  m/s (large)

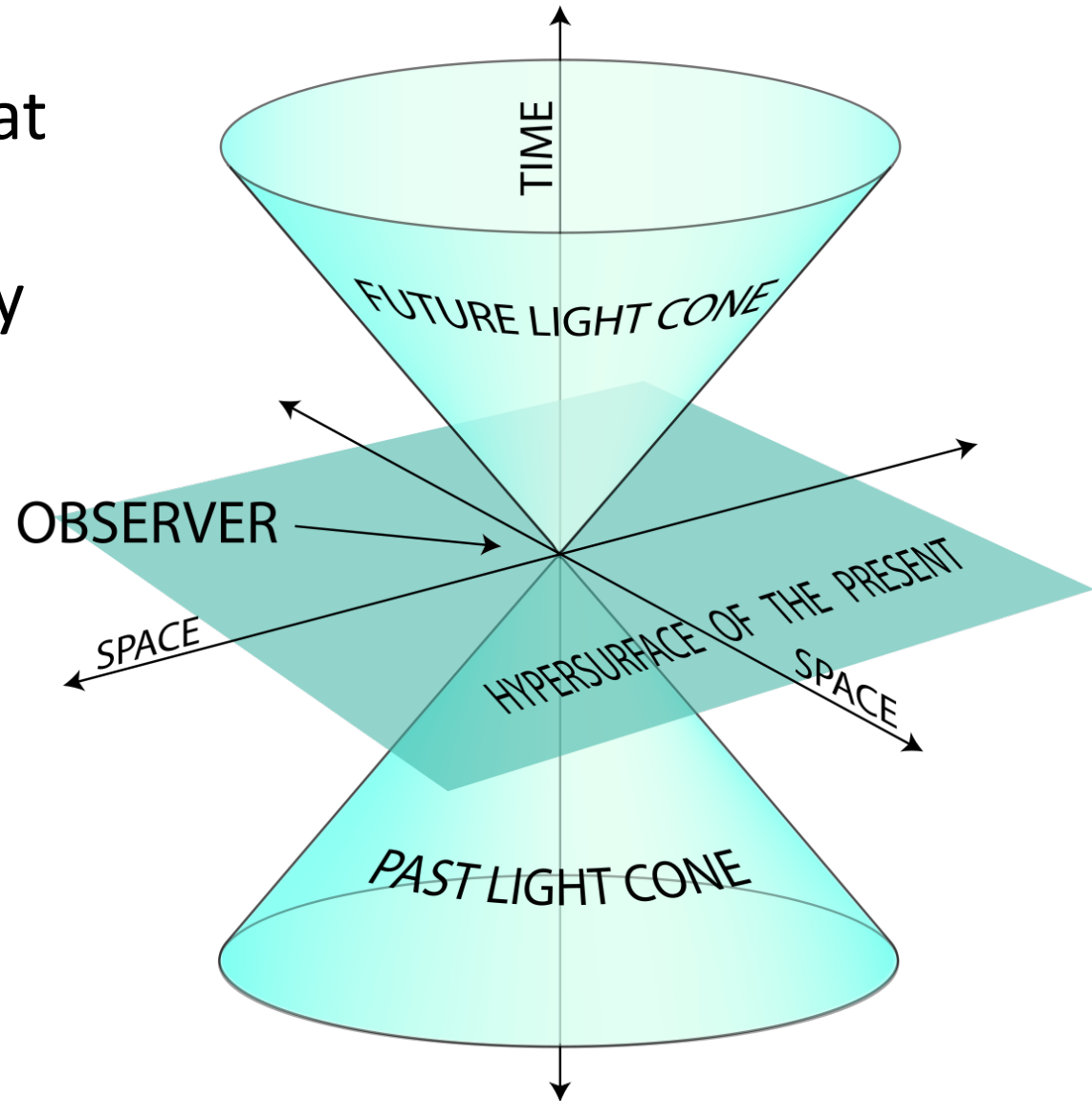


[https://www.ihkplus.de/Das\\_Ende\\_der\\_Ketteninsolvenz.AxCMS](https://www.ihkplus.de/Das_Ende_der_Ketteninsolvenz.AxCMS)

- **Consequences:** (1) bodies cannot move faster than  $c$ , (2)  $c$  is the same in all frames, (3) causality

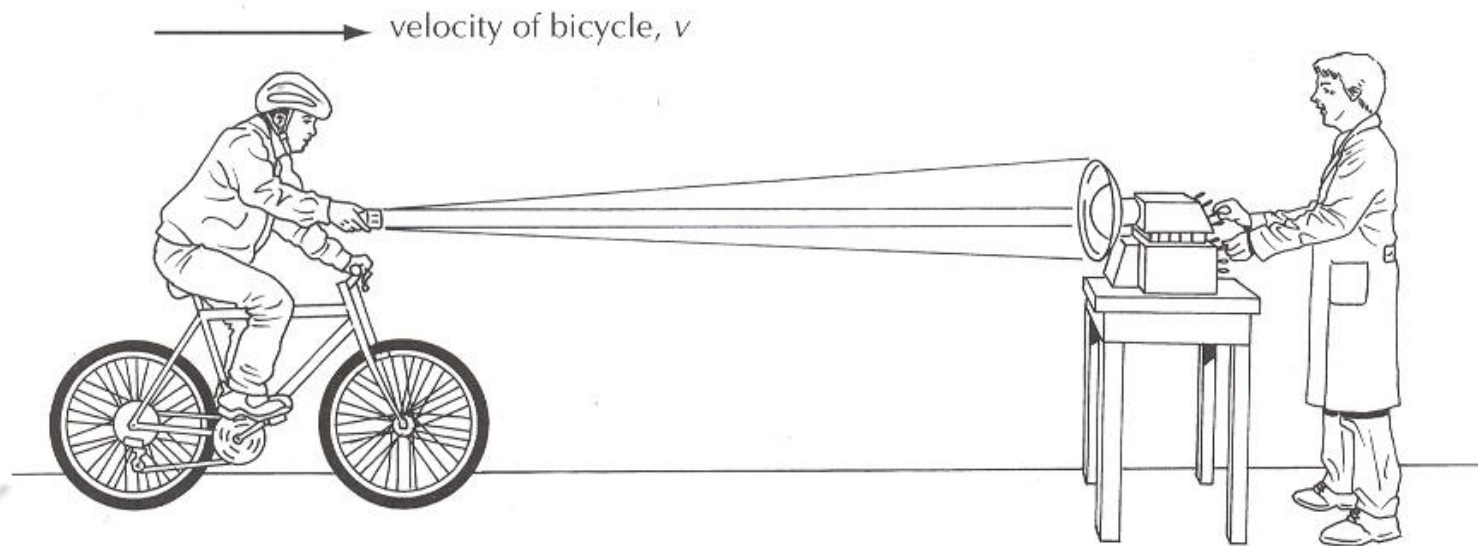
# The role of light

- The finite velocity at which signals can propagate is deeply connected to the idea of **causality**



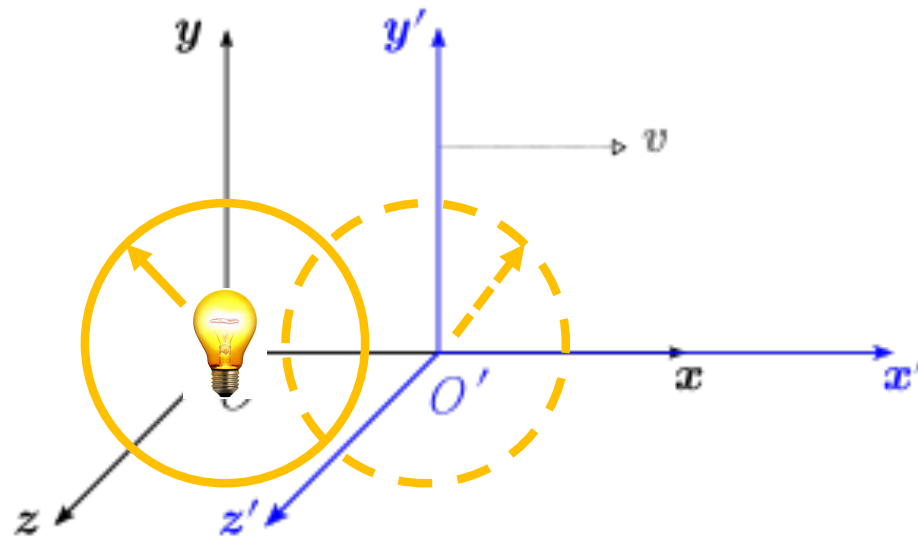
# Einstein's postulate

- Einstein's postulate (1905): **the speed of light is the same in all inertial frames** (regardless of the motion of the source/observer)
- The Galilean transformations are wrong!



# Lorentz transformations

- How should we transform the co-ordinates of events?
- Imagine sending out a light signal from the origin:



$$\text{In } S: \quad x^2 + y^2 + z^2 = (ct)^2$$

$$\text{In } S': \quad x'^2 + y'^2 + z'^2 = (ct')^2$$

# Lorentz transformations

- These equations are satisfied by the **Lorentz transformations**:

$$t' = \gamma(t - vx/c^2)$$

$$x' = \gamma(x - vt)$$

$$y' = y$$

$$z' = z$$

$$t = \gamma(t' + vx'/c^2)$$

$$x = \gamma(x' + vt')$$

$$y = y'$$

$$z = z'$$

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

# Simultaneity

- The Lorentz transformations have some remarkable consequences
- First, consider two events that are simultaneous in  $S$  ( $t_1 = t_2$ ). By the Lorentz transformations:

$$t'_1 - t'_2 = \frac{\gamma v}{c^2} (x_2 - x_1)$$

- **These events are not simultaneous in  $S'$ !**
- There is no such thing as absolute time, the order of events depends on the reference frame!

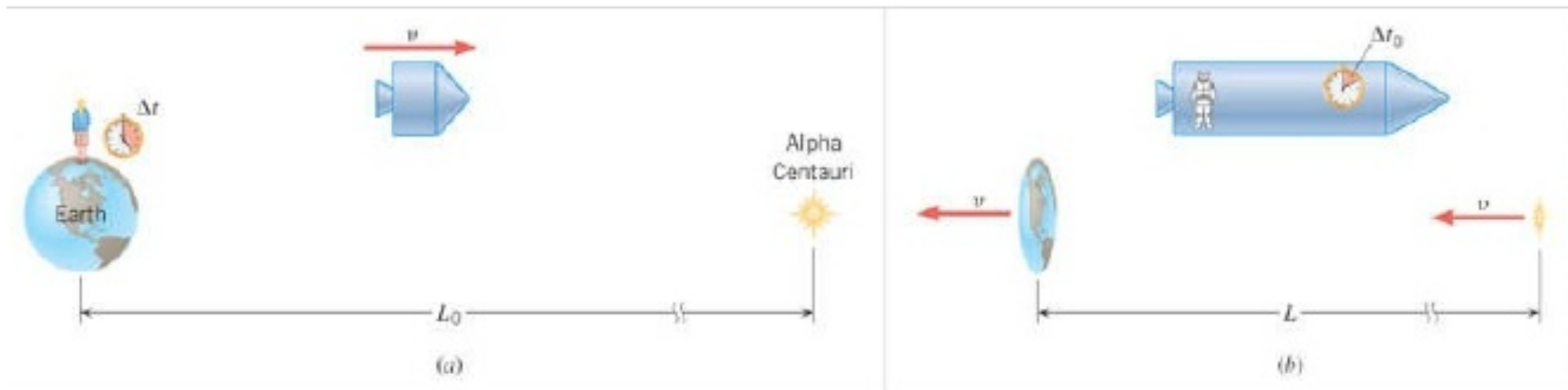


# Length contraction

- Consider a stick at rest in  $S'$  with ends at  $(x'_1, x'_2)$
- Observers in  $S$  measure its length by recording the end positions  $(x_1, x_2)$  simultaneously in  $S$ . They find:

$$x_2 - x_1 = (x'_2 - x'_1)/\gamma$$

- **The length of a moving object is contracted by  $\gamma$**

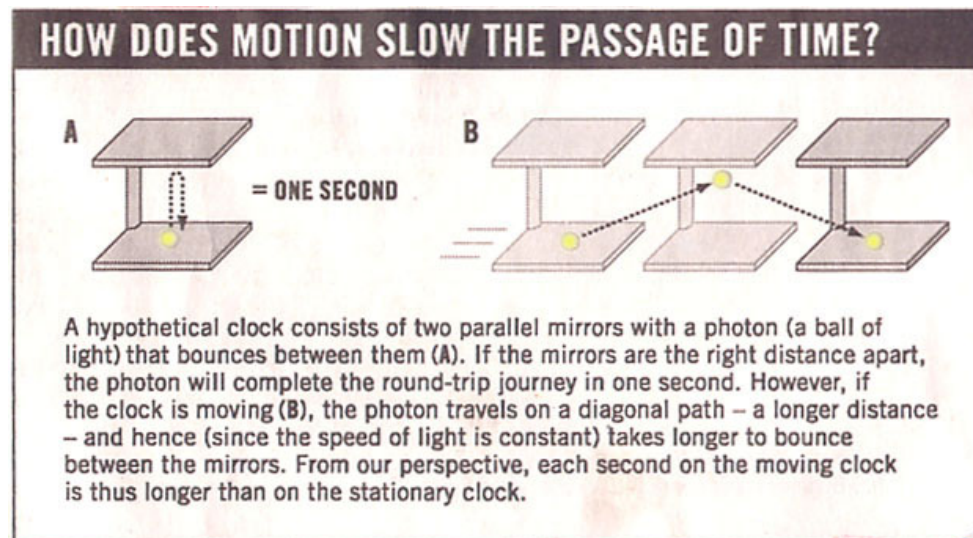


# Time dilation

- A clock at the origin of  $S'$  ticks at times  $(t'_1, t'_2)$
- The spacing of these ticks in  $S$  is:

$$t_2 - t_1 = \gamma(t'_2 - t'_1)$$

- **A moving clock ticks at longer intervals**



<https://patriceayme.wordpress.com/2014/06/17/time-dilation/>

# Space-time interval

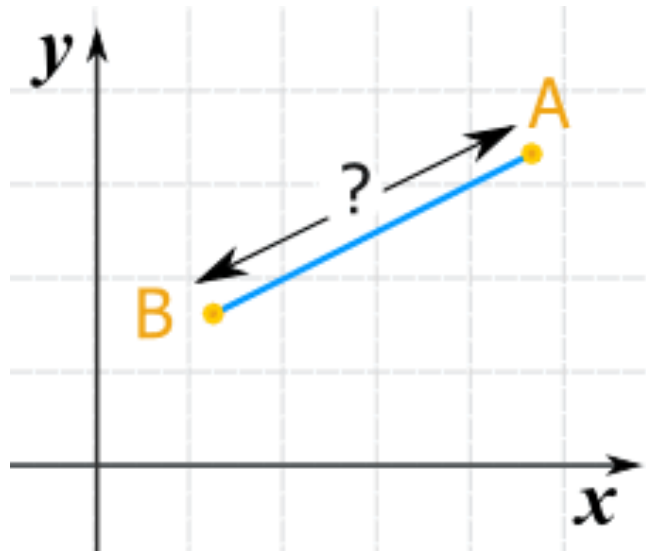
- The Lorentz transformation has a special property for how the difference in the space-time co-ordinates of two events transform between  $S$  and  $S'$ :

$$-c^2\Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2 = -c^2\Delta t'^2 + \Delta x'^2 + \Delta y'^2 + \Delta z'^2$$

- This combination is the **space-time interval**  $\Delta s^2$
- It is an **invariant** (has the same value in all frames)

# Importance of invariants

- **Invariants** – quantities which all observers agree to be the same – are useful!
- In Euclidean geometry, the distance between 2 points is the same if you rotate co-ordinates



The **space-time interval in relativity** (same in all inertial frames) is analogous to a **distance in Euclidean geometry** (same in all rotated frames)

# Classifying intervals

- The invariant space-time interval,  $\Delta s^2 = -c^2 \Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2$ , may be used to **classify pairs of events**
- Events for which  $\Delta s^2 < 0$  are **timelike** (“time wins”) – an inertial observer can pass through them both. The time between the events in this frame is the **proper time**  $\Delta \tau$
- Events for which  $\Delta s^2 > 0$  are **spacelike** – there’s an inertial frame in which they are simultaneous. The separation between the events in this frame is the **proper separation**.
- Events for which  $\Delta s^2 = 0$  are **lightlike** – they occur along the same light ray

# Relativistic momentum

- Conservation of momentum can be preserved if we **modify the concept of the mass of a particle such that it depends on velocity**

$$m(v) = \gamma m_0 = \frac{m_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$

- We have introduced the **rest mass**  $m_0$
- As  $v \rightarrow 0$  we recover classical momentum  $p = m_0 v$

# Relativistic energy

- Considering the work done on a particle  $\int \frac{dp}{dt} dx$  as the energy gained, we recover a modified expression for relativistic energy

$$E = \gamma m_0 c^2 = \frac{m_0 c^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

- Particles have a **rest energy**  $m_0 c^2$
- As  $v \rightarrow 0$  we find  $E = m_0 c^2 + \frac{1}{2} m_0 v^2$
- Mathematically we find:  $E^2 - p^2 c^2 = (m_0 c^2)^2$